# Self-Balancing Binary Search Trees

EECS 214, Fall 2018

### A self-balancing BST

Random binary search trees are *very likely* to be balanced Self-balancing trees are *guaranteed* to be balanced

# Balanced search tree survey

### **AVL** trees

Due to: Georgy Adelson-Velsky & Evgenii Landis (1962)

Main idea: Maintain a balance factor giving the difference

between each node's subtrees' heights

Local invariant: Balance factor between -1 and 1, maintained

via rotations

Global invariant: Tree is approximately height-balanced

### 2-3 trees

Due to: John Hopcroft (1970)

Main idea: 2-nodes have one element and two children;

3-nodes have two elements and three children

Local invariant: All subtrees of a node have the same height

Global invariant: Every leaf is at the same depth

Advantage: Faster insertions, slower lookups (compared to

AVL)

### **B**-trees

**Due to:** Rudolf Bayer & Ed McCreight (1971)

**Main idea:** Generalization of 2-3 trees up to k children.

**Local invariant:** Like 2–3 trees, but allow up to k/2 missing

children.

Global invariant: Every leaf is at the same depth

Use: On-disk databases (or modern memory hierarchies)

Advantage: Larger nodes means fewer disk accesses (or

cache misses)

### 2-3-4 trees (a/k/a 2-4 trees)

Due to: Rudolf Bayer (1972)

Main idea: B-tree of order 4.

Why interesting: Isometry of red-black tree

### Red-black trees

Due to: Leonidas J. Guibas & Robert Sedgewick (1978)

Main idea: Every node has an extra bit marking it "red" or "black"

Local invariant: No red node has a red parent

**Global invariant:** Equal number of black nodes from root to every leaf

**Advantage:** Faster insertions, slower lookups (compared to AVL); easier representation than 2–3(–4) trees

### Splay trees (randomized or amortized!)

Due to: Daniel Sleator & Robert Tarjan (1985)

Main idea: Cache recently accessed elements near the root of

the tree

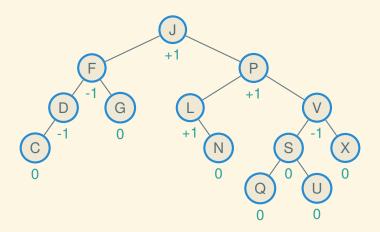
Local invariant: Complicated; required amortized analysis

**Global invariant:** Paths are *very likely* to be  $O(\log n)$ 

Advantage: Self optimizing; no extra balance data



# Example of an AVL tree

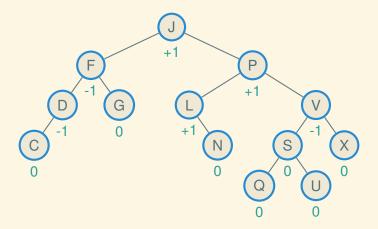


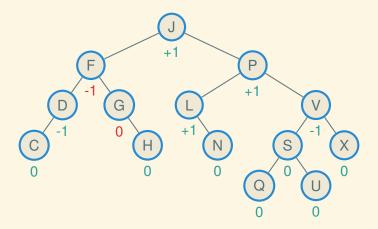
## Local invariant maintains global property

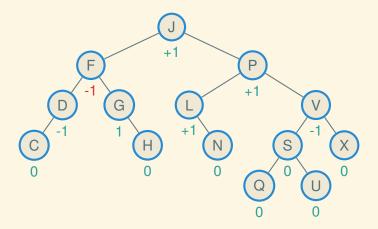
- Balance factors are maintained locally
- Never recompute them from scratch
- Yet the whole tree stays reasonably balanced

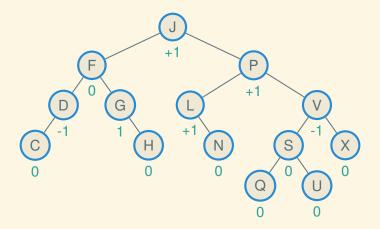
### **AVL** insertion

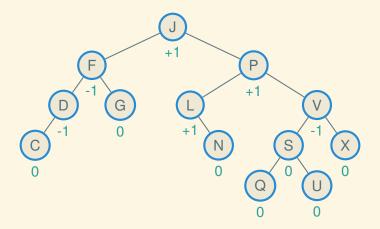
- First do a normal leaf insertion
- Track balance factors on the way back up to the root
- Adjust with rotations as necessary

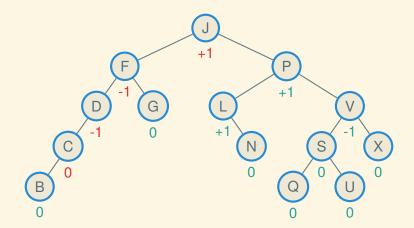


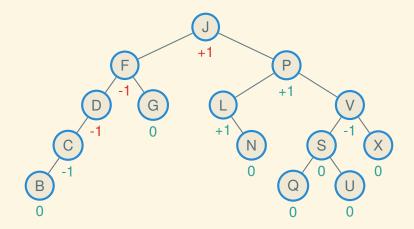


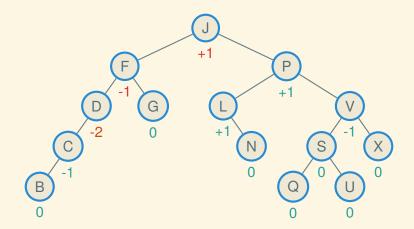


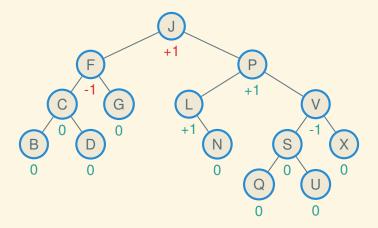


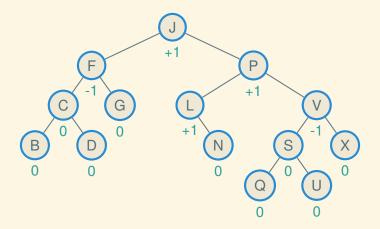




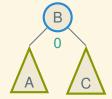






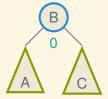


Suppose we have an AVL tree:



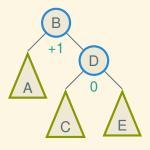
(Convention: triangles represent equal-height subtrees.)

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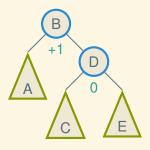
(Convention: triangles represent equal-height subtrees.)

Right now the balance factor is 0. So if we insert into A or C and that subtree grows in height, it becomes -1 or 1.



Right now the balance factor at B is +1.

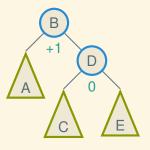
Suppose we insert into A. What happens to B's balance factor?



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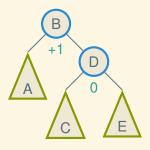
Suppose we insert into A. What happens to B's balance factor?

- If no change in A's height then no change in B's balance
- If A's height grows then B's balance factor goes to 0



Right now the balance factor at B is +1.

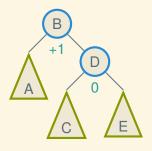
Suppose we insert into C. What happens to B's balance factor?



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Suppose we insert into C. What happens to B's balance factor?

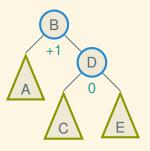
- If no height change then B's balance doesn't change
- If C grows then B's balance factor becomes +2



Right now the balance factor at B is +1.

Suppose we insert into C. What happens to B's balance factor?

- If no height change then B's balance doesn't change
- If C grows then B's balance factor becomes +2—not okay!



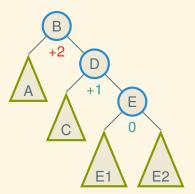
Right now the balance factor at B is +1.

Likewise, suppose we insert into E. What happens to B's balance factor?

- If no height change then B's balance doesn't change
- If E grows then B's balance factor becomes +2—not okay!

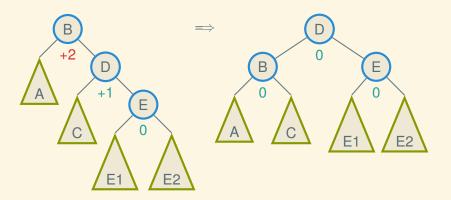
# The right-right case

If the height of the right-right subtree (E) increases, we get a situation like this:



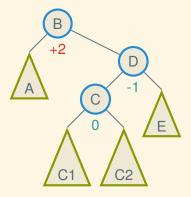
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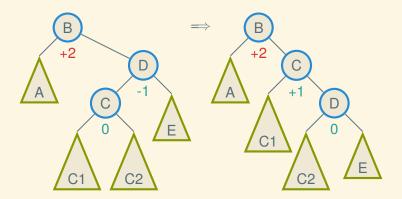
# The right-left case

If the height of the right-left subtree (C) increases, we get a situation like this:



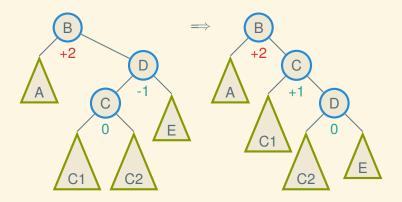
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If the height of the right-left subtree (C) increases, we get a situation like this:



But this is now the right-right case, which we know how to handle!

# Maintaining the AVL property

- We've seen the right-right and right-left cases
- The left-left and left-right cases are symmetrical
- Deletion is like ordinary BST deletion, with the same rebalancing cases

See avl.rkt.

# Red-black trees

#### The rules:

1. Nodes are colored red or black.

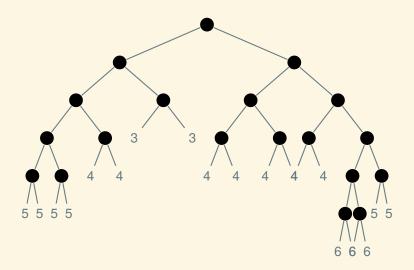
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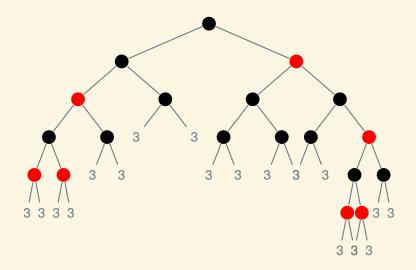
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- 4. Every red node has a black parent.

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- 3. "Dummy leaves" are black.
- 4. Every red node has a black parent.
- 5. For every node, all paths to leaves have the same "black height."

# Red-black colorability



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- 2. Color new node red.
- 3. If parent is also red (violating rule 4), color parent black and look for problems further up.

# Next time: C and C++