

Run-Time Polymorphism

CS 211

Winter 2020

Definition

polymorphism, *n.* (from *poly-* + *-morphism*)

1. The ability to assume different forms or shapes.
2. (biology) The coexistence, in the same locality, of two or more distinct forms independent of sex, not connected by intermediate gradations, ...
3. (object-oriented programming) The feature pertaining to the dynamic treatment of data elements based on their type, allowing for an instance of a method to have several definitions.
4. (mathematics, type theory) The property of certain typed formal systems of allowing for the use of type variables and binders/quantifiers over those type variables; ...
5. (crystallography) ...
6. (genetics) ...

Parametric polymorphism (in OCaml)

```
let mystery xs0 =  
  let rec loop acc xs =  
    match xs with  
    | []           -> acc  
    | x :: xs'    -> loop (x :: acc) xs'  
  in loop [] xs0
```

ML stands for meta-language

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Ad-hoc polymorphism

```
bool test(int v, int lo, int hi)
{
    return lo <= v && v < hi;
}
```

```
bool test(double v, double lo, double hi)
{
    return low <= v && v <= hi;
}
```

Generic = parametric + ad-hoc

```
template <class T>
void filter(std::vector<T>& v, T lo, T hi)
{
    size_t dst = 0;

    for (T& x : v)
        if (test(x, lo, hi))
            v[dst++] = x;

    v.resize(v.size() - dst);
}
```

Bounded parametric polymorphism

```
trait Testable {  
    fn test(&self, lo: &Self, hi: &Self) -> bool;  
}
```

```
impl Testable for f64 {  
    fn test(&self, lo: &f64, hi: &f64) -> bool  
    { lo <= self && self <= hi }  
}
```

```
fn filter<T: Testable>(v: &mut Vec<T>, lo: &T, hi: &T) {  
    let mut dst = 0;  
    for i in 0 .. v.len() {  
        if v[i].test(lo, hi) {  
            v.swap(dst, i);  
            dst += 1;  
        }  
    }  
}
```

Message/method polymorphism

```
Number subclass: Complex [  
  | realpart imagpart |  
  
  "constructor and setter omitted..."  
  
  real [ ^realpart ]  
  imag [ ^imagpart ]  
  
  + other [  
    ^Complex real: (realpart + other real)  
              imag: (imagpart + other imag)  
  ]  
  
  "etc..."  
]
```


Subtype polymorphism in theory

A type τ is a *subtype* of a type σ (notation: τ **is-a** σ) **iff** every value of type τ is also a value of type σ .

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Possible examples:

- `int is-a double ?`

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- Rectangle **is-a** Shape
- Square **is-a** Rectangle ?

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- Integer **is-a** Real
- Rectangle **is-a** Shape
- Square **is-a** Rectangle
- `vector<Rectangle>` **is-a** `vector<Shape>`
- `bool (*) (Shape)` **is-a** `bool (*) (Rectangle)` ?

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- `vector<Rectangle>` **is-a** `vector<Shape>`
- `bool (*) (Rectangle)` **is-a** `bool (*) (Shape)`

Subtype polymorphism in C++

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struct Base  
{ };
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Then:

- `Derived*` **is-a** `Base*`,
- `Derived&` **is-a** `Base&`, and
- and likewise for `const` versions, but
- `Derived` ~~**is-a**~~ `Base` – why not?

Adding “methods”

```
struct Base  
{ int f() { return 0; } };
```

```
struct Derived : Base  
{ int f() { return 1; } };
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```
TEST_CASE("direct")  
{  
    Base b;  
    Derived d;  
    CHECK( b.f() == 0 );  
    CHECK( d.f() == 1 );  
}
```


Adding “methods”

```
struct Base  
{ int f() { return 0; } };
```

```
struct Derived : Base  
{ int f() { return 1; } };
```

```
int g(Base& b) { return b.f(); }
```

```
TEST_CASE("via_reference")  
{  
    Base b;  
    Derived d;  
    CHECK( g(b) == 0 );  
    CHECK( g(d) == 0 ); // ???  
}
```

Static versus dynamic dispatch

To determine which function to call:

- Static dispatch uses the static type of the variable
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To get dynamic dispatch in C++, a function must be **virtual**

Introducing virtual functions

```
struct Base
{ virtual int f() { return 0; } };

struct Derived : Base
{ int f() override { return 1; } };
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struct Base
{ virtual int f() { return 0; } };

struct Derived : Base
{ int f() override { return 1; } };

int g(Base& b) { return b.f(); }

TEST_CASE("via_reference")
{
    Base b;
    Derived d;
    CHECK( g(b) == 0 );
    CHECK( g(d) == 1 );
}
```

– To CLion! –