Concurrent Objects and Linearizability

EECS 3/495 "Rust"

Spring 2017

What is a concurrent object?

- How do we describe one?
- How do we implement one?
- How do we tell if we're right?

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- How do we describe one?
- How do we tell if we're right?





q.enq(6)

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q.enq(6) q.deq()



q.enq(6) q.deq() \Rightarrow 2

Implementation: Lock-based ring buffer

```
#include <array>
```

```
template <typename Element, int capacity>
class Lock_based_FIFO
{
    public:
        void enq(Element);
        Element deq();
    }
}
```

```
private:
    std::array<Element, capacity> data_;
    unsigned head_ = 0, tail_ = 0;
    Lock lock_;
};
```

```
template <typename Element, int capacity>
void Lock_based_FIFO<Element, capacity>::enq(Element x)
{
    LockGuard guard(lock_);
    if (tail_ - head_ == capacity) throw fifo_full();
    data_[tail_++ % capacity] = x;
}
```

```
template <typename Element, int capacity>
Element Lock_based_FIFO<Element, capacity>::deq()
{
    LockGuard guard(lock_);
    if (tail_ == head_) throw fifo_empty();
    return data_[head_++ % capacity];
}
```

Now consider this

Same thing, but:

- no mutual exclusion
- only two threads:
 - one only enqueues
 - one only dequeues

Wait-free SRSW FIFO

```
#include <array>
#include <atomic>
```

```
template <typename Element, int capacity>
class Wf_SRSW_FIFO
{
    public:
        void enq(Element);
        Element deq();
```

private:

};

```
std::array<Element, capacity> data_;
std::atomic<unsigned long> head_{0}, tail_{0};
```

```
template <typename Element, int capacity>
void Wf_SRSW_FIFO<Element, capacity>::enq(Element x)
{
    if (tail_ - head_ == capacity) throw fifo_full();
    data_[tail_ % capacity] = x;
    ++tail_;
}
```

```
template <typename Element, int capacity>
Element Wf_SRSW_FIFO<Element, capacity>::deq()
{
    if (tail_ == head_) throw fifo_empty();
    Element result = data_[head_ % capacity];
    ++head_;
    return result;
}
```

}

What is a concurrent queue?

- Need a way to specify a concurrent queue object
- Need a way to prove that an algorithm implements the spec

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How do we specify objects?

Object specification

In a concurrent setting:

- it gets the right answer (correctness, a safety property)
- it doesn't get stuck (progress, a liveness property)

Let's start with correctness.

Sequential objects

Each object has:

- a state:
 - ► fields, usually
 - ► FIFO example: the sequence of elements
- a set of methods:
 - only way to access/manipulate the state
 - ► FIFO example: enq and deq methods

• If (precondition)

- ► the object is in such-and-such a state
- ► before you call the method,

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- then (postcondition)
 - the method will return a particular value
 - or throw a particular exception

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- ► the object is in such-and-such a state
- before you call the method,
- then (postcondition)
 - ► the method will return a particular value
 - or throw a particular exception
- and (postcondition)
 - the object will be in some specified state
 - when the method returns.

Example sequential specification: dequeue

- Precondition:
 - queue state is x_1, x_2, \ldots, x_k for $k \ge 1$
- Postcondition:
 - returns x_1
- Postcondition:
 - queue state is x_2, \ldots, x_k

Example sequential specification: dequeue

- Precondition:
 - queue state is x_1, x_2, \ldots, x_k for $k \ge 1$
- Postcondition:
 - returns x_1
- Postcondition:
 - queue state is x_2, \ldots, x_k

Easy!

Example sequential specification: dequeue

- Precondition:
 - queue is empty
- Postcondition:
 - throws fifo_empty exception
- Postcondition:
 - state is unchanged

Easy!

Sequential specifications are awesome!

- All method interactions captures by side-effects on state
- Each method described in isolation
- Can add new methods easily

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What about concurrent specification?

Complication: methods take time

- Sequential: what is time? who cares?
- Concurrent: method call is interval, not event

Complication: methods take overlapping time

- Sequential: what is time? who cares?
- Concurrent: method call is interval, not event
- Sequential: invariants must hold between calls
- Concurrent: overlapping means might never be between calls

The Big Question

What does it mean for a *concurrent* object to be correct?

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What does it mean for a *concurrent* object to be correct? Or, what is a concurrent FIFO queue? What does it mean for a concurrent object to be correct?

Or, what is a concurrent FIFO queue?

- FIFO means stuff happens in order
- concurrent means time/order is kinda ambiguous

Intuitively...

```
template <typename Element, int capacity>
void Lock_based_FIFO<Element, capacity>::enq(Element x) {
    LockGuard guard(lock_);
    if (tail_ - head_ == capacity) throw fifo_full();
    data_[tail_++ % capacity] = x;
}
```

```
template <typename Element, int capacity>
Element Lock_based_FIFO<Element, capacity>::deq() {
    LockGuard guard(lock_);
    if (tail_ == head_) throw fifo_empty();
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Intuitively...

}

```
template <typename Element, int capacity>
void Lock_based_FIFO<Element, capacity>::eng(Element x) {
    LockGuard guard(lock_);
    if (tail_ - head_ = capacity) throw fifo_full();
    data_[tail_++ \% capacity] = x;
}
template <typename Element, int capacity>
Element Lock_based_FIFO<Element, capacity>::deg() {
    LockGuard guard(lock_);
    if (tail_ == head_) throw fifo_empty();
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```

Mutual exclusion means we can describe the behavior sequentially

Linearizability

- Each method "takes effect" "instantaneously" between invocation and response events
- Object is correct if this "sequential" behavior is correct

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Such a concurrent object is linearizable

Is linearizability really obout the object?

A linearizable object: all of its possible executions are linearizable (Linearizable execution examples on board)

Formal model of executions

Split method call into two events:

Invocation	A q.enq(x)	Thread A calls q.enq(x)
Response	A q:void	Result is void

$$H = \begin{cases} A \text{ q.enq(3)} \\ A \text{ q:void} \\ B \text{ p.enq(4)} \\ B \text{ p:void} \\ B \text{ q.deq()} \\ B \text{ q:3} \end{cases}$$

Object projection:

 $\begin{array}{l} A \text{ q.enq(3)} \\ A \text{ q:void} \end{array}$ $H|q = B \text{ q.deq()} \\ B \text{ q:3} \end{array}$

Thread projection:

$$H|B = \begin{array}{c} B \text{ p.enq(4)} \\ B \text{ p:void} \\ B \text{ q.deq()} \\ B \text{ q:3} \end{array}$$

$$H = \begin{cases} A \text{ q.enq(3)} \\ A \text{ q:void} \\ B \text{ p.enq(4)} \\ B \text{ p:void} \\ B \text{ q.deq()} \\ B \text{ q:3} \end{cases}$$

Complete subhistories

Remove pending invocations:

H = B p.enq(4) B q.deq() H = B q.deq() B q.deq() B q:3

Complete subhistories

Remove pending invocations:

A q.enq(3) A q:void Complete(H) = B p.enq(4) B p:void B q.deq() B q:3

Sequential subhistories

Responses immediately follow invocations (except possibly a final invocation):

 $H = \begin{bmatrix} A \text{ q.enq(3)} \\ A \text{ q:void} \\ B \text{ p.enq(4)} \\ B \text{ p:void} \\ B \text{ q.deq()} \\ B \text{ q:3} \\ A \text{ q.deq()} \end{bmatrix}$

History well-formedness

$$H = \begin{cases} A \text{ q.enq(3)} \\ B \text{ p.enq(4)} \\ B \text{ p:void} \\ B \text{ q:deq()} \\ A \text{ q:void} \\ B \text{ q:3} \end{cases}$$

History well-formedness

$$H = \begin{cases} A \text{ q.enq(3)} \\ B \text{ p.enq(4)} \\ B \text{ p:void} \\ B \text{ q:deq()} \\ A \text{ q:void} \\ B \text{ q:3} \end{cases}$$

H is well formed if its thread projections are sequential:

History well-formedness

$$H = \begin{cases} A \text{ q.enq(3)} \\ B \text{ p.enq(4)} \\ B \text{ p:void} \\ B \text{ q:deq()} \\ A \text{ q:void} \\ B \text{ q:3} \end{cases}$$

H is well formed if its thread projections are sequential:

$$H|A = \begin{array}{c} A \text{ q.enq(3)} \\ A \text{ q:void} \end{array} \qquad H|B = \begin{array}{c} B \text{ p.enq(4)} \\ B \text{ p:void} \\ B \text{ q.deq()} \\ B \text{ q:3} \end{array}$$

History equivalence

 $H = \begin{cases} A \text{ q.enq(3)} \\ B \text{ p.enq(4)} \\ B \text{ p:void} \\ B \text{ q:deq()} \\ A \text{ q:void} \\ B \text{ q:3} \end{cases}$

 $G = \begin{cases} A \text{ q.enq(3)} \\ A \text{ q:void} \\ B \text{ p.enq(4)} \\ B \text{ p:void} \\ B \text{ q:deq()} \\ B \text{ q:3} \end{cases}$

History equivalence

 $H = \begin{array}{cc} A \text{ q.enq(3)} & A \\ B \text{ p.enq(4)} & A \\ B \text{ p:void} & G = \begin{array}{c} B \\ B \\ G \text{ q:deq()} & G \\ B \\ G \text{ q:void} & B \\ B \\ G \text{ q:3} & G \end{array}$

 $G = \begin{cases} A \text{ q.enq(3)} \\ A \text{ q:void} \\ B \text{ p.enq(4)} \\ B \text{ p:void} \\ B \text{ q:deq()} \\ B \text{ q:3} \end{cases}$

 $G \sim H$ iff threads see the same things:

 $H|\mathbf{A} = G|\mathbf{A}$ $H|\mathbf{B} = G|\mathbf{B}$

A sequential specification describes a legal single-thread, single-object history

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A grammar for (unbounded) FIFO histories:

$$\begin{array}{rcl} H & ::= & H_{\epsilon} \\ \\ H_{x_{1},...,x_{k}} & ::= \\ H_{x_{1},...,x_{k}} & ::= & q.enq(x); \ q:void; \ H_{x_{1},...,x_{k},x} \\ \\ H_{x_{0},x_{1},...,x_{k}} & ::= & q.deq(); \ q:x_{0}; \ H_{x_{1},...,x_{k}} \end{array}$$

Legal histories

A sequential (multi-object, multi-thread) history H is legal if:

For every object x, H|x is in the sequential spec for x.

Precedence

A method call *c precedes* a method call *d* if *c*'s response comes before *d*'s invocation

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Example:

A q.enq(3) B p.enq(4) B p:void A q:void B q.deq() B q:3

- Method call A q.enq(3) precedes method call B q.deq()
- Method call A q.enq(4) precedes method call B q.deq()
- Method call A q.enq(3) does not precede method call B q.enq(4)

Properties of precedence

- In general, it's a partial order
- For a sequential history, it's a total order

Have we seen this before?

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- In general, it's a partial order
- For a sequential history, it's a total order

Have we seen this before?

Yes: Precedence is *happens-before* (\rightarrow) for method call intervals

Linearizability, formally

History H is *linearizable* if it can be extended to complete history G by

- appending responses to some pending invocations, and/or
- discarding the remaining pending invocations

such that there exists some legal sequential history $S \sim G$ where $\rightarrow_H \subseteq \rightarrow_S$

 $H = \begin{bmatrix} A \text{ q.enq(3)} \\ B \text{ q.enq(4)} \\ B \text{ q:void} \\ B \text{ q.deq()} \\ B \text{ q:4} \\ B \text{ q.enq(6)} \end{bmatrix}$

 $H = \begin{bmatrix} A \text{ q.enq(3)} \\ B \text{ q.enq(4)} \\ B \text{ q:void} \\ B \text{ q.deq()} \\ B \text{ q:4} \\ B \text{ q.enq(6)} \end{bmatrix} = G = G$

A q:void

A q.enq(3)Bq.enq(4)B q:void H = B q.deq() G = B q.deq() S = A q:voidB q:4 Bq.enq(6)

A q.enq(3)Bq.enq(4)B q:void B q:4

A q:void

Bq.enq(4)B q:void A q.enq(3)B q.deq() B q:4



- S is legal and sequential
- $S \sim G$
- $\rightarrow_H \subseteq \rightarrow_S$

Composability theorem

History *H* is linearizable if for every object *x*, H|x is linearizable

Composability theorem

History *H* is linearizable if for every object *x*, H|x is linearizable

This means we can reason about objects independently

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