

CS 395/495-26: Spring 2002

IBMR: Week 7A

New Direction: Applying Projections

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Reminders

No midterm, no final, but ...
Alternating homework / project

- Project 2 Due today (C* part optional)
- Homework 1 due Thurs May 16
- Project 3 Due Thurs May 24
- Revised Syllabus...

Recutting the Course Content

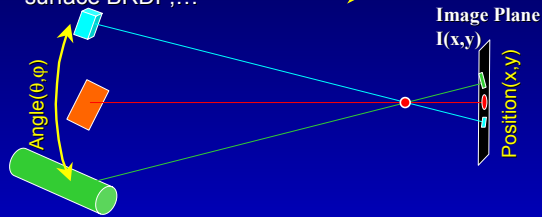


- 4 weeks left: More Fun, More Imaging, Less math
- More Project / CG work, Less Book Deciphering...
- Revised Topics:
 - 2D Warps of all kinds
 - non-planar projections
 - panorama building, camera error correction (spherical)
 - Light Probes
 - 3D/2D: Camera Matrix (Ch 5)
 - 3D: Epipolar Geom. (Ch 8)

An Image Is...

Light + 3D Scene: Illumination, shape, movement, surface BRDF, ...

2D Image: Collection of rays through a point



'Image' : Angle \rightarrow Position Map

- So far:
 - planar perspective projection
 - P^2 , P^3 projective transformations
 - how to find these transformations from images.
- But Planar Perspective Projection is just **ONE KIND** of image, and
- P^2 and P^3 linear projective transformation H is just **ONE KIND** of image warping
$$H = H_S H_A H_P$$

'Image' : Angle \rightarrow Position Map

- **All Cameras** make mistakes (geometry, shading/vignetting) book corrects them; we'll ignore them.
- Many kinds of camera projections
- 'Funhouse Mirrors'
 - Non-planar perspective projections:
 - Spherical, Conical, cylindrical, hyperbolic
- Applications: Panoramas, 'Light Probes' ...

Image Warping: General Idea

2D→2D continuous coordinate map, a 'rubber sheet'
 – Notation: $\text{input}(x,y) \rightarrow \text{output}(u,v)$

- Demo: <http://www.angelfire.com/biz/beamersandblasters/PicWarp.html>.
- Usually done patch-by-patch, with polynomials

$$u = u(x,y) = \begin{bmatrix} 1 & y & y^2 \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} \begin{bmatrix} 1 \\ x \\ x^2 \end{bmatrix}$$

$$v = v(x,y) = \dots$$

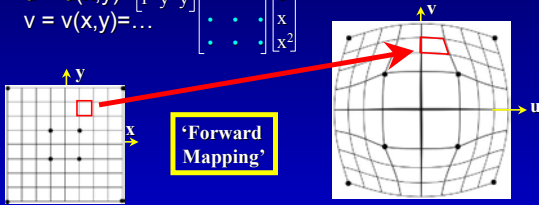


Image Warping: General Idea

2D→2D continuous coordinate map, a 'rubber sheet'

- **PROBLEM:** How would you undo such a warp?
- **Answer:** 'inverse mapping'; iterate in (u,v)

$$x = x(u,v) = \begin{bmatrix} 1 & v & v^2 \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} \begin{bmatrix} 1 \\ u \\ u^2 \end{bmatrix}$$

$$y = y(u,v) = \dots$$

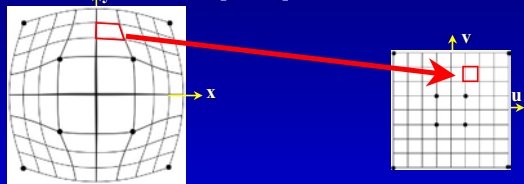


Image Warping: General Idea

2D→2D continuous coordinate map, a 'rubber sheet'

- **PROBLEM:** How would you undo such a warp?
- **2nd Answer:** 'parameter mapping'; iterate in (s,t)

$$x = x(s,t) = \begin{bmatrix} 1 & t & t^2 \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} \begin{bmatrix} 1 \\ s \\ s^2 \end{bmatrix}$$

$$y = y(s,t) = \dots$$

$$u = u(s,t)$$

$$v = v(s,t)$$

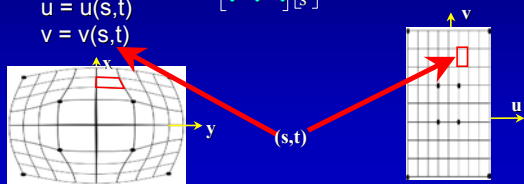


Image Warping: General Idea

2D→2D continuous coordinate map, a 'rubber sheet'

• **PROBLEM:** How would you undo such a warp?

• **Answer:** 'inverse mapping'; iterate in (u,v)

$$\begin{aligned}x &= x(u,v) = \begin{bmatrix} 1 & v & v^2 \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} \begin{bmatrix} 1 \\ u \\ u^2 \end{bmatrix} \\ y &= y(u,v) = \dots\end{aligned}$$

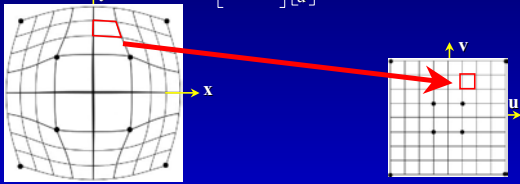


Image Warping: General Idea

2D→2D continuous coordinate map: 'rubber sheet'

PROBLEM: inverse **required** sometimes (mess)

PROBLEM: pixels aren't continuous; sampling errors

- aliasing (output pixels skip some input pixels)
- holes (input pixels skip some output pixels)

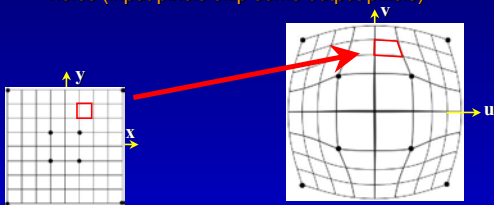


Image Warping: IBMR Form

2D→2D continuous coordinate map: 'rubber sheet'

PROBLEM: inverse **required** sometimes (mess)

IBMR Answer: H matrix is invertible

PROBLEM: pixels aren't continuous; sampling errors

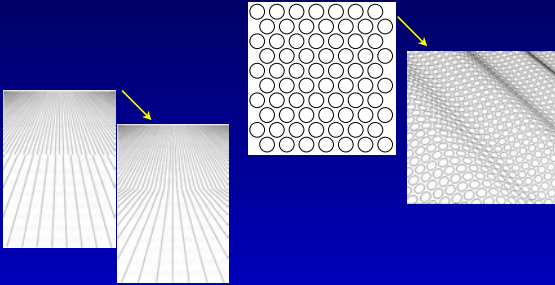
IBMR Answer: Use vertices, not pixels:

let OpenGL texture mapping keep the image "continuous"



Image Warping: IBMR Form

- Projective transformation H in P^2 is a 'warp'
- But many more **kinds** of warps possible!



Panoramas: Planar 'Bow-Tie'

- For limited-size mosaics only (angle limits)
- Find all H from correspondence in overlapped regions
- Choose a (central) reference image (book pg. 196)
- Reproject, cross-dissolve in reference image plane



Panoramas: Sphere / Cylinder

- Assemble from P^2 Correspondences:
 - Find H to link each image only to its neighbors
- Spherical/Cylindrical? Do this **last**
 - CAN'T convert planar-spherical & then easily align in 2D because...
 - Spherical images behave poorly near poles
 - e.g. 'Can't comb the hairs on a tennis ball'
 - (no uniform 2D rectangular sampling grid exists)

Panorama Making

Planar:

- Start with overlapped planar proj. images
- Do 4-point corresp. (or better) for alignment
- Merge images by cross-dissolve

Early IBR: QuickTime VR (Chen, Williams '93)

1) Four Planar Images \rightarrow 1 Cylindrical Panorama:

IN:

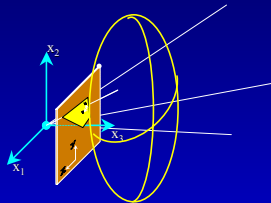


OUT:



Image Warping: IBMR Form

- Especially useful: 3D-like warps in P2:
- Plane is just ONE of many shapes formed by varying x_2 ...
- Spherical, Cylindrical, Parabolic, Hyperbolic...



Early IBR: QuickTime VR (Chen, Williams '93)

2) Windowing, Horizontal-only Reprojection:



Light Probes: What?

- Photograph a mirrored sphere
- warp image to find irradiance .vs. direction

1 picture ==
half-sphere

High contrast?
Full sphere?
More Pictures!



END
