#### Introduction to Real-Time Systems

#### ECE 397-1

#### Northwestern University

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### Goals for lecture

- · Handle a few administrative details
- Form lab groups
- Broad overview of real-time systems
- · Definitions that will come in handy later
- Example of real-time sensor network

## Administrative tasks

- Backgrounds
- Question rule
- · Office hours

## Backgrounds

- Lab teams had best be balanced (low-level vs. high-level experience)
- Name
- Which are you better at?
  - Low-level ANSI-C/assembly experience
  - High-level object-oriented programming experience
- · What's your major?

### Question rule

- · If something in lecture doesn't make sense, please ask
- · You're paying a huge amount of money for this
- Letting something important from lecture slip by for want of a question is like burning handfulls of money

### Core course goal

By the end of this course, we want you to learn how to build real-time systems and build a useful real-time sensor network.

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#### ° Office hours

• When shall I schedule my office hours?

#### Homework index

1 Reading assignment (for next class) . . . . .

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### Today's topics

- · Taxonomy of real-time systems
- · Optimization and costs
- · Definitions
- Optimization formulation
- · Overview of primary areas of study within real-time systems





### Taxonomy: Static

- · Task arrival times can be predicted.
- · Static (compile-time) analysis possible.
- Allows good resource usage (low processor idle time proportions).
- Sometimes designers shoehorn dynamic problems into static formulations allowing a good solution to the wrong problem.

# Taxonomy: Soft real-time

- · More slack in implementation
- · Timing may be suboptimal without being incorrect
- Problem formulation can be much more complicated than hard real-time
- Two common (and one uncommon) methods of dealing with non-trivial soft real-time system requirements
  - Set somewhat loose hard timing constraints
  - Informal design and testing
  - Formulate as optimization problem

## Taxonomy: Dynamic

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- Task arrival times unpredictable.
- · Static (compile-time) analysis possible only for simple cases.
- Even then, the portion of required processor utilization efficiency goes to 0.693.
- In many real systems, this is very difficult to apply in reality (more on this later).
- Use the right tools but don't over-simplify, e.g.,
  - We assume, without loss of generality, that all tasks are independent.
  - If you do this people will make jokes about you.

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### Taxonomy: Hard real-time

- · Difficult problem. Some timing constraints inflexible.
- · Simplifies problem formulation.

# Taxonomy: Periodic

- Each task (or group of tasks) executes repeatedly with a particular period.
- · Allows some nice static analysis techniques to be used.
- · Matches characteristics of many real problems...
- ... and has little or no relationship with many others that designers try to pretend are periodic.

### Taxonomy: Periodic $\rightarrow$ Single-rate

- One period in the system.
- · Simple.
- · Inflexible.
- · This is how a lot of wireless sensor networks are implemented.

### Taxonomy: Periodic $\rightarrow$ Multirate

- · Multiple periods.
- Can use notion of circular time to simplify static (compile-time) schedule analysis E. L. Lawler and D. E. Wood,
  "Branch-and-bound methods: A survey," *Operations Research*, pp. 699–719, July 1966.
- · Co-prime periods leads to analysis problems.

### Taxonomy: Periodic $\rightarrow$ Other

- It is possible to have tasks with deadlines less than, equal to, or greater than their periods.
- Results in multi-phase, circular-time schedules with multiple concurrent task instances.
  - If you ever need to deal with one of these, see me (take my code). This class of scheduler is nasty to code.

## Taxonomy: Aperiodic

- Also called sporadic, asynchronous, or reactive
- · Implies dynamic
- · Bounded arrival time interval permits resource reservation
- Unbounded arrival time interval impossible to deal with for any resource-constrained system

### Definitions

- Task
- Processor
- Graph representations
- Deadline violation
- Cost functions

Definitions: Task

- · Some operation that needs to be carried out
- · Atomic completion: A task is all done or it isn't
- · Non-atomic execution: A task may be interrupted and resumed

### Definitions: Processor

- · Processors execute tasks
- · Distributed systems
  - Contain multiple processors
  - Inter-processor communication has impact on system performance
  - Communication is challenging to analyze
- · One processor type: Homogeneous system
- · Multiple processor types: Heterogeneous system

## Task/processor relationship



Relationship between tasks, processors, and costs E.g., power consumption or worst-case execution time

## Graph definitions



- Set of vertices (V)- usually operations
- Set of edges (*E*)– directed or undirected relationships on vertex pairs

### Example graph classifications



### Some graph uses

- Problem representations
- · Timing constraint specification
- Resource binding
- And many more...



#### Back to real-time problem taxonomy:

#### Jagged edges

- Some things dramatically complicate real-time scheduling
- These are horrific, especially when combined
  - Data dependencies
  - Unpredictability
  - Distributed systems
- These are irksome
  - Heterogeneous processors
  - Preemption

<sup>33</sup> Allocation, assignment and scheduling

#### How does one best

- Analyze problem instance specifications
  - E.g., worst-case task execution time
- · Select (and build) hardware components
- · Select and produce software
- · Decide which processor will be used for each task
- · Determine the time(s) at which all tasks will execute

### <sup>™</sup> Operating systems and scheduling

How does one best design operating systems to

- Support sufficient detail in workload specification to allow good control, e.g., over scheduling, without increasing design error rate
- Design operating system schedulers to support real-time constraints?
- · Support predictable costs for task and OS service execution

### Central areas of real-time study

- · Allocation, assignment and scheduling
- Operating systems and scheduling
- · Distributed systems and scheduling
- · Scheduling is at the core or real-time systems study

### Allocation, assignment and scheduling

- · In order to efficiently and (when possible) optimally minimize
  - Price, power consumption, soft deadline violations
- · Under hard timing constraints
- · Providing guarantees whenever possible
- · For all the different classes of real-time problem classes

This is what I did for a Ph.D.

## Distributed systems and scheduling

How does one best dynamically control

- · The assignment of tasks to processing nodes...
- ... and their schedules

for systems in which computation nodes may be separated by vast distances such that

- · Task deadline violations are bounded (when possible)...
- · ... and minimized when no bounds are possible

This is part of what Professor Dinda did for a Ph.D.

### Optimization

Thinking of a design problem in terms of optimization gives design team members objective criterion by which to evaluate the impact of a design change on quality.

- · Still need to do a lot of hacking
- · Know whether its taking you in a good direction

## The value of formality: Optimization and costs

- The design of a real-time system is fundamentally a cost optimization problem
- Minimize costs under constraints while meeting functionality requirements
  - Slight abuse of notation here, functionality requirements are actually just constraints
- · Why view problem in this manner?
- · Without having a concrete definition of the problem
  - How is one to know if an answer is correct?
  - More subtly, how is one to know if an answer is optimal?

#### Summary

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- Real-time systems taxonomy and overview
- Definitions
- Importance of problem formulation

• J. W. S. Liu, *Real-Time Systems*. Prentice-Hall, Englewood Cliffs, NJ, 2000

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- Chapter 2
- Start on Chapter 3